

## General Description

The Gotop GPM-1000-UB is a complete GPS engine module that features superior sensitivity, ultra low power and small form factor. The GPS signal is applied to the antenna input of module, and a complete serial data message with position, velocity and time information is presented at the serial interface with NMEA protocol or custom protocol.

Its  $-162\text{dBm}$  tracking sensitivity extends positioning coverage into place like urban canyons and dense foliage environment where the GPS was not possible before. The small form factor and low power consumption make the module easy to integrate into portable device like Notebook PC, mobile phones, cameras and vehicle navigation systems.

## Applications

- Notebook PC
- MID
- UMPC
- NB



**Figure 1: GPM-1000-UB Top View**

## Features

- Build on high performance, low-power UBLOXchipset
- Ultra high sensitivity:  $-162\text{dBm}$
- I/O PIN: Reference PCI Express mini card form factor (refer page 3)
- Extremely fast TTFF at low signal level
- Built in high gain LNA
- Low power consumption: Max  $60\text{mA}@3.3\text{V}$
- NMEA-0183 compliant protocol or custom protocol
- Operating voltage:  $2.95\text{V}$  to  $3.6\text{V}$
- Operating temperature range:  $-40$  to  $85^\circ\text{C}$
- Environment: fits into laptops mini-PCI-E slot
- Small form factor:  $50.95\text{mm} \times 30.0\text{mm} \times 4.0\text{mm}$
- Weight:  $6.0\text{g}$
- interface keyword: USB1.1/2.0
- RoHS compliant (Lead-free)

## Performance Specification

Parameter	Specification	
Receiver Type	L1 frequency band, C/A code, 50-channels SBAS: WAAS, EGNOS, MSAS, GAGAN	
Sensitivity	Tracking	-162dBm
	Acquisition	-160dBm
Accuracy	Position	5m CEP without SA
	Velocity	0.1m/s without SA
	Timing (PPS)	60ns RMS
Acquisition Time	Cold Start	48s
	Warm Start	35s
	Hot Start	1s
	Re-Acquisition	<1s
Power Consumption	Tracking	60mA @3.3V Vcc
	Acquisition	50mA
	Sleep/Standby	TBD
NavigationDataUpdate Rate	1Hz	
Operational Limits	Altitude	Max 18,000m
	Velocity	Max 515m/s
	Acceleration	Less than 4g

## Interfaces Configuration

**Power Supply:** Regulated power for the GPM-1000-UB is required. The input voltage Vcc should be 3.3V  $\pm$ 10%, maximum, current is no less than 100mA. Suitable decoupling must be provided by external decoupling circuitry.

**Antenna:** The GPM-1000-UB GPS receiver is designed for supporting the active antenna or passive antenna connected with pin RF\_IN. The gain of active antenna should be no less than 28dB. The maximum noise figure should be no more than 2.5dB and output impedance is at 50 Ohm.

**Pin Description**

Pin#	Name	Pin#	Name
51		52	+3.3V
49		50	GND
47		48	
45		46	
43		44	
41		42	
39		40	GND
37		38	USB_D+
35	GND	36	USB_D-
33		34	GND
31		32	
29	GND	30	
27	GND	28	
25		26	GND
23		24	
21	GND	22	
19		20	
17		18	GND
<b>Mechanical Key</b>			
15	GND	16	
13		14	
11		12	
9	GND	10	
7		8	
5		6	
3		4	GND
1		2	+3.3V

- \* Reserved for future second PCI Express Lane (if needed)
- \*\* Reserved for future Subscriber Identity Module (SIM) interface (if needed)
- \*\*\* Reserved for future wireless disable signal (if needed)
- \*\*\*\* Reserved for future wireless coexistence control interface (if needed)



Environment				
Storage Temperature	Tstg	-40	125	°C
Humidity			95	%

Note: Absolute maximum ratings are stress ratings only, and functional operation at the maxims is not guaranteed. Stress beyond the limits specified in this table may affect device reliability or cause permanent damage to the device. For functional operating conditions, refer to the operating conditions tables as follow.

### Operating Conditions

Parameter	Symbol	Condition	Min	Typ	Max	Units
Power supply voltage	V <sub>CC</sub>		3.0	3.3	3.6	V
Power supply voltage ripple	V <sub>CC_PP</sub>	V <sub>CC</sub> =3.0V		55		mV
Consumption current	I <sub>CC</sub>	V <sub>CC</sub> =3.0V		60	55	mA
Input high voltage	V <sub>IH</sub>		0.7xV <sub>CC</sub>		V <sub>CC</sub> +1.0	V
Input low voltage	V <sub>IL</sub>		-0.3		0.3xV <sub>CC</sub>	V
Output high voltage	V <sub>OH</sub>		0.8xV <sub>CC</sub>		V <sub>CC</sub>	V
Output low voltage	V <sub>OL</sub>		0		0.2xV <sub>CC</sub>	V
Operating temperature	T <sub>opr</sub>		-40		85	°C

### NMEA 0183 Protocol

The NMEA protocol is an ASCII-based protocol, Records start with a \$ and with carriage return/line feed. GPS specific messages all start with \$GPxxx where xxx is a three-letter identifier of the message data that follows. NMEA messages have a checksum, which allows detection of corrupted data transfers.

The Gotop GPM-1000-UB supports the following NMEA-0183 messages: GGA, GLL, GSA, GSV, RMC and VTG.

**Table 1: NMEA-0183 Output Messages**

NMEA Record	DESCRIPTION
GGA	Global positioning system fixed data
GLL	Geographic position—latitude/longitude
GSA	GNSS DOP and active satellites
GSV	GNSS satellites in view
RMC	Recommended minimum specific GNSS data
VTG	Course over ground and ground speed

**GGA-Global Positioning System Fixed Data**

Table 2 contains the values of the following example:

\$GPGGA, 161229.487,3723.24754,N, 12158.34164,W, 1,07,1.0,9.0,M.0000\*18

**Table 2: GGA Data Format**

Name	Example	Units	Description
Message ID	\$GPGGA		GGA protocol header
UTC Position	161229.487		hhmmss.sss
Latitude	3723.24574		ddmm.mmmmm
N/S indicator	N		N=north or S=south
Longitude	12158.34164		dddmm.mmmmm
E/W Indicator	W		E=east or W=west
Position Fix Indicator	1		See Table 2-1
Satellites Used	07		Range 0 to 12
HDOP	1.0		Horizontal Dilution of Precision
MSL Altitude	9.0	meters	
Units	M	meters	

Geoids Separation		meters	
Units	M	meters	
Age of Diff.Corr.		second	Null fields when DGPS is not Used
Diff.Ref.Station ID	0000		
Checksum	*18		
<CR> <LF>			End of message termination

**Table 2-1: Position Fix Indicators**

Value	Description
0	Fix not available or invalid
1	GPS SPS Mode, fix valid
2	Differential GPS, SPS Mode, fix valid
3	GPS PPS Mode, fix valid

**GLL-Geographic Position – Latitude/Longitude**

Table 3 contains the values of the following example:

\$GPGLL , 3723.24754, N,12158.34164, W,161229.487, A\*2C.

**Table 3: GLL Data Format**

Name	Example	Units	Description
Message ID	\$GPGLL		GLL protocol header
Latitude	3723.24754		ddmm.mmmmm
N/S Indicator	N		N=north or S=south
Longitude	12158.34164		dddmm.mmmmm
E/W Indicator	W		E=east or W=west
UTC Position	161229.487		hhmmss.sss
Status	A		A=data valid or V=data not valid

Checksum	*2C		
<CR> <LF>			End of message termination

**GSA-GNSS DOP and Active Satellites**

Table 4 contains the values of the following example:

\$GPGSA , A, 3, 07, 02, 26,27, 09, 04,15, , , , , , 1.8,1.0,1.5\*33.

**Table 4: GSA Data Format**

Name	Example	Units	Description
Message	\$GPGSA		GSA protocol header
Mode 1	A		See Table 4-2
Mode 2	3		See Table 4-1
Satellite Used	07		Sv on Channel 1
Satellite Used	02		Sv on Channel 2
...	...		...
Satellite Used			Sv on Channel 12
PDOP	1.8		Position Dilution of Precision
HDOP	1.0		Horizontal Dilution of Precision
VDOP	1.5		Vertical Dilution of Precision
Checksum	*33		
<CR> <LF>			End of message termination

**Table 4-1: Mode 1**

Value	Description
1	Fix not available
2	2D
3	3D



**Table 4-2: Mode 2**

Value	Description
M	Manual-forced to operate in 2D or 3D mode
A	Automatic-allowed to automatically switch 2D/3D

### GSV-GNSS Satellites in View

Table 5 contains the values of the following example:

\$GPGSV , 2, 1, 07, 07, 79,048, 42, 02, 51,062, 43, 26, 36,256, 42, 27, 27, 138,42\*71

\$GPGSV, 2, 2, 07, 09, 23,313, 42, 04, 19, 159, 41, 15,12,041, 42\*41.

**Table 5: GGA Data Format**

Name	Example	Units	Description
Message ID	\$GPGSV		GSV protocol header
Number of Message	2		Range 1 to 3
Message Number	1		Range 1 to 3
Satellites in View	07		
Satellite ID	07		Channel 1(Range 1 to 32)
Elevation	79	degrees	Channel 1(Maximum 90)
Azinmuth	048	degrees	Channel 1(True, Range 0 to 359)
SNR(C/NO)	42	dBHz	Range 0 to 99,null when not tracking
...			...
Satellite ID	27		Channel 4(Range 1 to 32)
Elevation	27	degrees	Channel 4(Maximum 90)
Azimuth	138	degrees	Channel 4(True, Range 0 to 359)
SNR(C/NO)	42	dBHz	Range 0 to 99, null when not tracking
Checksum	*71		

<CR> <LF>			End of message termination
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Depending on the number of satellites tracked multiple messages of GSV data may be required.

### RMC-Recommended Minimum Specific GNSS Data

Table 6 contains the values of the following example:

\$GPRMC, 161229.487, A, 3723.24754, N, 12158.34164, W, 0.13,309.62, 120598,, \*10

**Table 6: RMC Data Format**

Name	Example	Units	Description
Message ID	\$GPRMC		RMC protocol header
UTS Position	161229.487		hhmmss.sss
Status	A		A=data valid or V=data not valid
Latitude	3723.24754		ddmm.mmmmm
N/S Indicator	N		N=north or S=south
Longitude	12158.34164		dddmm.mmmmm
E/W Indicator	W		E=east or W=west
Speed Over Ground	0.13	Knots	
Course Over	309.62	Degrees	True
Ground			
Date	120598		Dummy
Magnetic variation		Degrees	E=east or W=west
Checksum	*10		
<CR> <LF>			End of message termination

### VTG-Course Over Ground and Ground Speed

Table 7 contains the values of the following example:

\$GPVTG, 309.62, T, M, 0.13, N, 0.2, K\*6E

**Table 7: VTG Data Format**

Name	Example	Units	Description
Message ID	\$GPVTG		VTG protocol header
Course	309.62	Degrees	Measured heading
Reference	T		True
Course		Degrees	Measured heading
Reference	M		Magnetic
Speed	0.13	Knots	Measured horizontal speed
Units	N		Knots
Speed	0.2	Km/hr	Measured horizontal speed
Units	K		Kilometer per hour
Checksum	*6E		
<CR> <LF>			End of message termination

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